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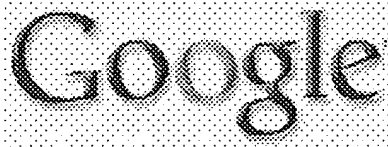
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Ioannis K. Nikolos ; Kimon P. Valavanis ; Nikos C. Tsourveloudis ; Anargyros N. Kostaras ;
Transactions on Systems, Man, and Cybernetics - Part B: Cybernetics : Accepted future publication , 2003
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2 **IEEE standard glossary of computer graphics terminology**
IEEE Std 610.6-1991 , 13 March 1992

[Abstract]   [PDF Full-Text (1464 KB)] **IEEE STD**

3 **Hysteresis loss analysis based on W/sub h/-B/sub m/ function**
Cheng, Z.; Takahashi, N.; Hu, Q.; Fan, C.;
Computation in Electromagnetics, 2002. CEM 2002. The Fourth International
Conference on (Ref. No. 2002/063) , 8-11 April 2002
Page(s): 2 pp.

[Abstract]   [PDF Full-Text (250 KB)] **IEE CNF**

4 **TEAM-based benchmark family: Problem 21/21/sup +/ /21**
Cheng, Z.; Takahashi, N.; Hu, Q.; Fan, C.;
Computation in Electromagnetics, 2002. CEM 2002. The Fourth International
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1 **Handling complexity in object based modeling and simulation**
Sharpe, J.E.E.; Bracewell, R.H.;
Tools for Simulation and Modelling (Ref. No. 2000/043), IEE Seminar on , 27 Ma
2000
Page(s): 1/1 -1/4

[Abstract]   [PDF Full-Text (200 KB)] **IEE CNF**

2 **Robust recognition of calibration charts**
Soh, L.M.; Kittler, J.;
Image Processing and Its Applications, 1997., Sixth International Conference or
Volume: 2 , 14-17 July 1997
Page(s): 487 -491 vol.2

[Abstract]   [PDF Full-Text (968 KB)] **IEE CNF**

3 **Robust scene interpretation of underwater image sequences**
Fairweather, A.J.R.; Hodgetts, M.A.; Greig, A.R.;
Image Processing and Its Applications, 1997., Sixth International Conference or
Volume: 2 , 14-17 July 1997
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[Abstract]   [PDF Full-Text (548 KB)] **IEE CNF**

4 **Using eye vergence to interact with objects in the 3-D space created b
stereoscopic display**
Istance, H.; Howarth, P.;

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Genetic Algorithms in Image Processing and Vision, IEE Colloquium on , 1994
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2 **Three-dimensional echocardiographic reconstruction and geometric aі of the human mitral valve**
Handschumacher, M.D.; Sanfilippo, A.J.; Harrigan, P.; Weyman, A.E.; Levine, R
Computers in Cardiology 1988. Proceedings. , 25-28 Sept. 1988
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[Abstract]   [PDF Full-Text (48 KB)] **IEEE CNF**

3 **Morphological skeleton transforms for determining position and orien᠄ of pre-marked objects**
Zhou, Z.; Smith, K.C.; Benhabib, B.; Safaee-Rad, R.;
Communications, Computers and Signal Processing, 1989. Conference Proceediı
IEEE Pacific Rim Conference on , 1-2 June 1989
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[Abstract]   [PDF Full-Text (384 KB)] **IEEE CNF**

4 **Grasping polyhedral objects with slip**
Gopalswamy, S.; Fearing, R.S.;
Robotics and Automation, 1989. Proceedings., 1989 IEEE International Confereі
14-19 May 1989

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4 **3-D position sensing using a single camera approach**
Cardillo, J.; Sid-Ahmed, M.A.; Soltis, J.J.;
Circuits and Systems, 1989., Proceedings of the 32nd Midwest Symposium on ,
Aug. 1989

Page(s): 325 -328 vol.1

[Abstract]   [PDF Full-Text (284 KB)] **IEEE CNF**

5 **From partial derivatives of 3-D density images to ridge lines**
Monga, O.; Benayoun, S.; Faugeras, O.D.;
Computer Vision and Pattern Recognition, 1992. Proceedings CVPR '92., 1992 II
Computer Society Conference on , 15-18 June 1992
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[Abstract]   [PDF Full-Text (512 KB)] **IEEE CNF**

6 **Selecting distinctive scene features for landmarks**
Li, S.; Tsuji, S.;
Robotics and Automation, 1992. Proceedings., 1992 IEEE International Conferei
12-14 May 1992
Page(s): 53 -59 vol.1

[Abstract]   [PDF Full-Text (952 KB)] **IEEE CNF**

7 **Determining location and orientation of a labelled cylinder using point
estimation algorithm**
Yuan-Chiuan You; Jiann-Der Lee; Jau-Yien Lee; Chin-Hsing Chen;
Pattern Recognition, 1992 . Vol.1. Conference A: Computer Vision and Applicati
Proceedings., 11th IAPR International Conference on , 30 Aug.-3 Sept. 1992
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[Abstract]   [PDF Full-Text (260 KB)] **IEEE CNF**

8 **Recognition of multiple objects using geometric hashing techniques**
Edwards, J.; Shoureshi, R.;
Decision and Control, 1993., Proceedings of the 32nd IEEE Conference on , 15-1
1993
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9 **Ratio of infarct subtended volume to surface area by 3-D echocardiogi
in vivo measurement of infarct dilation and aneurysm formation**
King, D.L.; Gopal, A.S.; Schroder, K.M.; Sapin, P.M.; King, D.L., Jr.; Shen, Z.;
Computers in Cardiology 1993. Proceedings. , 5-8 Sept. 1993
Page(s): 17 -20

[Abstract]   [PDF Full-Text (356 KB)] **IEEE CNF**

10 **Differential volume rendering: a fast volume visualization technique** 1
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11 **Duality of reconstruction and positioning from projective views**
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13 **Visual control of an autonomous vehicle using neural networks**
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14 **A model-based gaze tracking system**
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–	52345	600/$.ccls.	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/25 11:11
–	37295	382/$.ccls.	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/25 11:11
–	9516	((3d or three$1dimension$3 or (three near dimension$3))) with (((position or location) and (orientation or direction)) or pose)	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/25 11:12
–	22094	((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) and (orientation or direction)) or pose)	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/25 11:14
–	17393	((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/25 11:14
–	6571	(((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/25 11:16
–	872	((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/25 11:16
–	428	(((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same (imag$3)	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/25 15:54

-	29	382/154.ccls. and ((((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same (imag$3))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/25 11:26
-	1	382/287.ccls. and ((((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same (imag$3))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/25 11:18
-	2	382/291.ccls. and ((((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same (imag$3))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/25 11:18
-	0	382/298.ccls. and ((((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same (imag$3))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/25 11:18
-	0	382/216.ccls. and ((((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same (imag$3))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/25 11:18
-	0	345/95.ccls. and ((((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same (imag$3))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/25 11:18
-	56	600/$.ccls. and ((((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same (imag$3))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/25 11:18
-	80	382/$.ccls. and ((((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same (imag$3))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/25 11:18

–	4	("4396945" | "4649504" | "5227985" | "5530771").PN.	USPAT	2003/09/25 12:26
–	14	5828770.URPN.	USPAT	2003/09/25 12:28
–	1	5828770.pn. and (stereo$7)	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/25 15:09
–	67	(((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same ((single or one) near5 (imag$3))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/25 16:12
–	51	(((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same ((single or one) near3 (imag$3))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/29 13:06
–	1	5751843.pn.	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/25 16:50
–	5	("4748676" | "4776464" | "5072294" | "5285273" | "5452370").PN.	USPAT	2003/09/25 17:17
–	11	5751843.URPN.	USPAT	2003/09/25 17:18
–	4876	(3d or three$1dimension$3 or (three near dimension$3)) same ((single or one) near2 (imag$3))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/29 13:08
–	1373	(3d or three$1dimension$3 or (three near dimension$3)) with ((single or one) near (imag$3))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/29 13:08
–	556	(3d or three$1dimension$3 or (three near dimension$3)) near3 ((single or one) near (imag$3))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/29 13:09
–	83	382/$.ccls. and ((3d or three$1dimension$3 or (three near dimension$3)) near3 ((single or one) near (imag$3)))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/29 13:09
–	0	382/$.ccls. and ((3d or three$1dimension$3 or (three near dimension$3)) near3 ((single or one) near (imag$3 and (camera or ccd))))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/29 13:10
–	7	((3d or three$1dimension$3 or (three near dimension$3)) near3 ((single or one) near (imag$3 and (camera or ccd))))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/29 13:16
–	10320	(object or subject) same (indicat$4 or marker or mark$4 or point$1) same ((three or ((3d or three$1dimension$3 or (three near dimension$3)) near3 ((single or one) near (imag$3)))) near ("D" or dimension$4))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/29 13:15
–	4915	(object or subject) with (indicat$4 or marker or mark$4 or point$1) with ((three or ((3d or three$1dimension$3 or (three near dimension$3)) near3 ((single or one) near (imag$3)))) near ("D" or dimension$4))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/29 13:15

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-	403	((object or subject) with (indicat$4 or marker or mark$4 or point$1) with ((three or ((3d or three$1dimension$3 or (three near dimension$3)) near3 ((single or one) near (imag$3)))) near ("D" or dimension$4))) with (imag$3 and (camera or ccd))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/29 13:18
-	225	(((object or subject) with (indicat$4 or marker or mark$4 or point$1) with ((three or ((3d or three$1dimension$3 or (three near dimension$3)) near3 ((single or one) near (imag$3)))) near ("D" or dimension$4))) with (imag$3 and (camera or ccd))) not (stereo$6)	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/29 13:17
-	6	((object or subject) with (indicat$4 or marker or mark$4 or point$1) with ((three or ((3d or three$1dimension$3 or (three near dimension$3)) near3 ((single or one) near (imag$3)))) near ("D" or dimension$4))) with ((single or one) near3 (imag$3 and (camera or ccd)))	USPAT; US-PGPUB; EPO; JPO; IBM_TDB	2003/09/29 13:18